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## **CLAIM LISTING**

1.(Currently Amended) An apparatus for stitching together two or more stacked planar layers, said apparatus including:

a stitch head mounted at a fixed location and actuatable to insert a stitch through a stack of two or more planar layers located beneath said stitch head;

a substantially horizontally oriented bed for supporting said stack of planar layers for manually guided movement across said bed beneath said stitch head;

detector means for detecting movement of a surface of said stack <u>oriented</u>

<u>parallel to said bed and proximate to said stitch head for producing signals representing the magnitude of stack surface movement; and</u>

control circuit means responsive to said signals indicating stack surface movement exceeding a certain threshold for actuating said stitch head to insert a stitch through said stack.

2.(Original) The apparatus of claim 1 wherein said stitch head includes a needle mounted for reciprocal movement substantially perpendicular to said bed between a full up position and a full down position; and wherein

said control circuit means for actuating said stitch head includes means for applying power to said stitch head to cause said needle to traverse one cycle from said full up position to said full down position to said full up position.

3.(Original) The apparatus of claim 2 wherein said means for applying power includes a motor/brake assembly operable in a motor mode for moving said needle and a brake mode for stopping movement of said needle.

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1	4. (Original) The apparatus of claim 2 wherein said means for applying power
2.	includes a motor and a clutch/brake assembly; and wherein
3	said clutch/brake assembly is operable in a clutch mode for coupling said
4	motor to said stitch head for moving said needle and a brake mode to stop movement of
5	said needle.
6	
7	5. (Original) The apparatus of claim 1 wherein said bed defines a flat
8	substantially horizontal surface for supporting said stack of planar layers; and wherein
9	said stitch head includes a needle mounted for movement substantially
10	perpendicular to said bed surface between a full up position and a full down position
11	whereat it pierces said planar layers supported on said bed surface.
12	
13	6. (Original) The apparatus of claim 5 wherein said control circuit means for
14	actuating said head includes means for selectively applying power to said stitch head to
15	cause said needle to move from said full up position to said full down position.
16	
17	7. (Original) The apparatus of claim 6 further including means for returning said
18	needle from said full down position to said full up position.
19	
20	8. (Currently Amended) The apparatus of claim 1 wherein said detector
21	means includes a light source for illuminating said stack surface; and
22	means for processing light reflected from said illuminated layer stack
23	surface for determining the magnitude of movement of said stack surface.
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25	<i>//</i>
26	//
27	<i>II</i>
28	<i>//</i>
29	<i>//</i>
30	<i>II</i>
31	<i>//</i>

1	9.(Original) The apparatus of claim 1 wherein said detector means includes
2.	optical means for measuring movement of said stack surface along orthogonal X and Y
3	axes; and
4	signal processing means responsive to said measured movement for
5	determining the magnitude of resultant movement of said stack; and wherein
6	said control circuit means actuates said stitch head when the magnitude of
7	said resultant movement exceeds a predetermined stitch length.
8	
9	10.(Currently Amended) A machine for stitching at least one fabric layer, said
10 ່	machine comprising:
11	an upper arm and a lower arm mounted in vertically spaced substantially
12	parallel relationship to define a throat space therebetween;
13	a substantially horizontally oriented plate on said lower arm for supporting
14	said fabric layer for guided movement in said throat space;
15	a needle arm supported from said upper arm above said plate actuatable
16	to insert a stitch into said fabric layer;
17	a detector for detecting movement of a surface of said fabric layer oriented
18	parallel to said plate and in said throat space; and
19	control circuitry responsive to detected movement of said fabric layer
20	surface for controlling actuation of said needle arm.
21	
22	11.(Original) The machine of claim 10 wherein said detector operates to produce
23	X and Y signals respectively representing the magnitude of translational movement of
24	said fabric layer surface along perpendicular X and Y axes.
25	
26	12. (Original) The machine of claim 10 wherein said detector operates to detect
27	movement of said fabric layer surface without physically contacting said fabric layer.
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29	<b>//</b>
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1	13.(Currently Amended) The machine of claim 10 wherein said detector
2 · '	includes:
3	a window oriented to collect energy from said fabric layer surface
4	proximate oriented parallel to said plate, and
5 '	signal processing means responsive to energy collected by said window
6	for producing signals representing the magnitude of movement of said fabric layer
7	across said plate.
8	
9	14. (Original) The machine of claim 13 wherein said detector includes a source of
10	energy for illuminating said fabric layer surface to reflect energy into said window.
11	
12	15. (Original) The machine of claim 14 wherein said source of energy comprises
13	a light source and said window collects light images reflected from said fabric layer
14	surface.
15	
16	16. (Original) The machine of claim 13 wherein said produced signals represent
17	translational movement of said fabric layer surface along perpendicular X and Y axes.
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19	<i>//</i>
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21	<i>''</i>
22	<i>//</i>
23	<i>''</i>
24	<i>//</i>
25	II
26	II .
27	II
28	II
29	//
30	II .
31	//

1 17. (Original) The machine of claim 10 wherein said needle arm includes a 2 needle mounted for cyclic movement between an up position spaced from said plate 3 and a down position piercing said fabric layer proximate to said plate; and wherein 4 said control circuitry is actuatable for moving said needle through at least 5 one cycle comprising needle motion from said up position to said down position to said 6 up position. 7 8 18. (Original) The machine of claim 17 wherein said control circuitry includes a 9 needle drive means for moving said needle through a cyclic movement in response to a 10 certain magnitude of fabric layer movement detected by said detector. 11 12 19. (Original) The machine of claim 18 further including user means for adjusting 13 the value of said certain magnitude. 14 15 20. (Original) The machine of claim 17 wherein said control circuitry includes a needle drive means for repeatedly cyclically moving said needle at a rate related to the 16 17 speed of fabric layer surface movement detected by said detector. // 18 19 // 20 // 21 // 22 // 23 // 24 // 25 // 26 // 27 II28 // 29 // 30 //

1 21.(Currently Amended) A quilting apparatus for inserting stitches of uniform 2 length through a stack of one or more fabric layers, said apparatus comprising: 3 a stitch head; 4 a bed defining a substantially horizontally oriented planar surface mounted 5 opposite to said stitch head, said planar surface being configured to support said stack 6 for guided movement across said planar surface; 7 said stitch head including a needle operable to execute a cyclic movement 8 from an up position remote from said planar surface to a down position piercing said 9 stack on said planar surface, and back to said up position; 10 a detector defining a window for collecting energy from a target area 11 substantially coincident with a surface of said stack oriented parallel to said planar 12 surface; and 13 signal processing means responsive to said collected energy for indicating 14 the magnitude of stack translational movement across said planar surface; and 15 control means responsive to a translational movement of said stack of a 16 magnitude exceeding a certain threshold for causing said needle to execute said cyclic 17 movement. 18 19 22. (Original) The quilting apparatus of claim 21 wherein said detector includes: 20 a light source mounted to illuminate said stack surface in said target area; 21 and wherein 22 said window is oriented to collect light images reflected from said target 23 area. 24 // 25 // 26 // 27 // 28 // 29 II30 // 31 //

4 1	22 (Compath, Amended). A method of forming consequence stitches of uniform
1	23.(Currently Amended) A method of forming successive stitches of uniform
2.	length through a stack of fabric layers having top and bottom surfaces, said method
3.	comprising:
4	mounting an actuatable stitch head at a fixed location;
5	manually moving said stack of fabric layers across a horizontal planar
6	surface under said stitch head;
7	detecting the movement of at least one of said stack surfaces oriented
8	parallel to said horizontal planar surface proximate to said stitch head; and
9 '	actuating said stitch head in response to a certain magnitude of detected
10	stack movement to insert a stitch through said stack of fabric layers.
11	
12	24. (Original) The method of claim 23 wherein said step of mounting said stitch
13	head includes mounting a needle for cyclic vertical movement between an up position
14	spaced from said stack and a down position penetrating said stack moving across said
15	planar surface.
16	
17	25. (Original) The method of claim 23 wherein said step of detecting the
18	movement of said stack includes:
19	providing an energy source for illuminating a target area of a surface of
20	said stack;
21	collecting energy images reflected from said target area; and
22	processing said collected energy images to determine the magnitude of
23	movement of said stack.
24	
25	26. (Original) The method of claim 23 wherein said step of actuating said stitch
26	head includes moving said needle through a single cyclic movement in response to
27	each increment of stack movement greater than said certain magnitude.
28	
29	27. (Original) The method of claim 23 wherein said step of actuating said stitch
30	head includes repeatedly cyclically moving said needle at a rate related to the speed of
31	stack movement.

1	28. (Currently Amended) A method of forming successive stitches of uniform
2 ·	length through a stack of one or more fabric layers having top and bottom surfaces, said
3	method comprising:
4	providing a horizontally oriented planar surface for supporting said stack
5	for guided movement across said planar surface;
6	mounting a stitch head opposite to said planar surface where said stitch
7	head is selectively actuatable to insert a stitch through said stack layers;
8	manually moving said stack across said planar surface;
9	optically observing a target area coincident with one of said stack surfaces
10	oriented parallel to said planar surface to determine the magnitude of stack movement
11 '	proximate to said planar surface; and
12	responding to a magnitude of movement greater than a certain threshold
13	for actuating said stitch head to insert a stitch into said stack.
14	
15	29.(Original) The method of claim 28 wherein said step of moving said stack
16	comprises a user manually grasping said fabric layers to push/pull said stack across
17	said planar surface.
18	
19	30. (Original) The method of claim 28 wherein said stack is mounted on a frame;
20	and wherein
21	said step of moving said stack comprises a user manually grasping said
22	frame to push/pull said stack across said planar surface.
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27	<i>//</i>
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29	<i>II</i>
30	H
31	H

1	31. (Original) A quilting apparatus for inserting stitches into a stack of one or
2 ,	more fabric layers, said apparatus comprising:
3	a stitch head;
4	a bed defining a substantially horizontally oriented planar surface mounted
5	opposite to said stitch head, said planar surface being configured to support said stack
6	for guided movement of said stack across said planar surface;
7	said stitch head including a needle operable to insert a stitch into said
8	stack by executing a cyclic movement including a needle-up position remote from said
9	planar surface and a needle-down position piercing said stack proximate to said planar
10	surface;
11	a detector for measuring the movement of said stack across said planar
12	surface proximate to said stitch head; and
13	control means for causing said needle to execute cyclic movements at a
14	rate substantially proportional to the rate of stack movement measured by said detector.
15	
16	32. (Original) The apparatus of claim 31 wherein said detector operates to
17	measure the magnitude of translational movement of said stack along orthogonal
18	directions.
19	
20	33. (Original) The apparatus of claim 32 wherein said control means causes said
21	needle to execute one cyclic movement for each threshold unit of movement measured
22	by said detector.
23	
24	34. (Original) The apparatus of claim 31 wherein said stack of fabric layers
25	includes an exterior stack surface; and wherein
26	said detector measures stack movement by measuring translational
27	movement of said exterior stack surface.
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